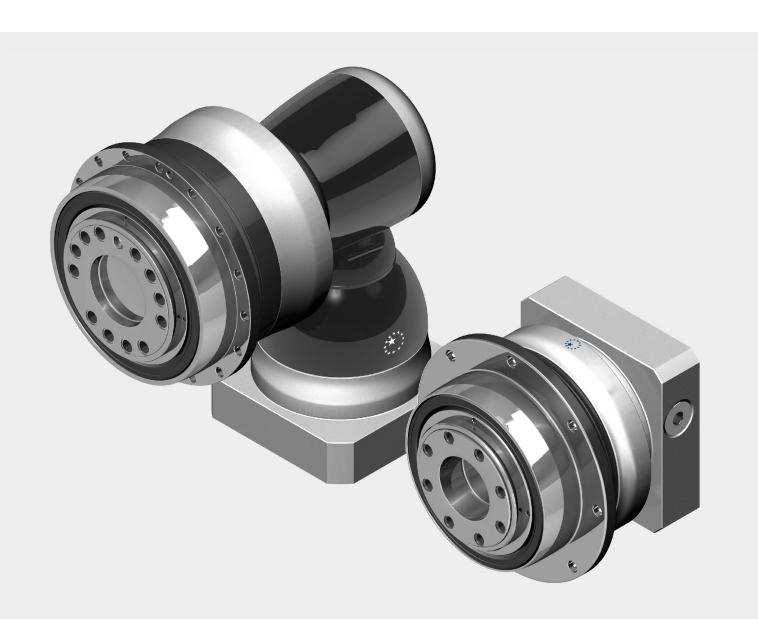


APEX DYNAMICS, INC.

NEW GENERATION PLANETARY GEARBOX

AH / AHK Series



Gearbox Series - AH / AHK

Features:

High Torque

High efficiency

Long-Term persistence of reduced backlash

Low noise

Long service life

Limited temperature rise

Optimized output torque

Optimized Inertia moment

Flexible mounting diameters









Ordering Code - AH / AHK Gearbox

AH090	_	005 ⁽¹⁾	/	MOTOR
AHK090	_	005 ⁽¹⁾	/	MOTOR
AHKA285 (3)				Motor Type
AHKB090 (3)				
				Ratio

Gearbox Size

Gearbox Size

AH 064 / 090 / 110 / 140 / 200 / 255 / 285 / 355 / 450 AHK 064 / 090 / 110 / 140 / 200 / 255 / 285 / 355 / 450

Ratio⁽²⁾

AH 4/5/7/10

16/20/21/25/28/31/35/40/46/50/61/70/91/100

AHK (2 Stg.) 12 / 15 / 16 / 20 / 25 / 28 / 35 / 40 / 49 / 50 / 70 / 100

AHKA (3 Stg.) 100 / 125 / 140 / 175 / 200 / 250 / 350 / 500 / 700 / 1,000

AHKB (3 Stg.) 64 / 84 / 100 / 125 / 140 / 175 / 200 / 250 / 280 / 350 / 400 / 500 / 700 / 1,000

AHK (4 Stg.) 1,225 / 1,400 / 1,750 / 2,000 / 2,800 / 3,500 / 5,000 / 7,000 / 10,000

AHKC 4/5/7/8/10/21/31/46/61/91

Motor Type

Manufacturer and Model

- (I) Ratio (i= N_{in}/N_{out}).
- (2) Please refer to the specifications for the ratios provided in each series.
- (3) Please refer to page 06.



Performance - AH Gearbox

Model No.	Model No.		Ratio ⁽¹⁾	AH064	AH090	AHII0	AH140	AH200	AH255	AH285	AH355	AH450	
			4	95	195	350	600	1,290	-	-	-	-	
		ı	5	80	165	305	525	1,145	1,745	3,285	-	-	
		•	7	60	130	250	435	980	1,495	2,525	-	-	
			10	24	55	160	305	700	1,070	1,810	-	-	
			16	95	195	360	615	1,320	-	-	-	-	
			20	95	200	360	615	1,320	1,770	3,325	-	-	
			21	80	165	310	535	1,165	1,770	3,330	5,595	10,915	
			25	80	165	310	535	1,165	1,770	3,330	-	-	
Nominal Output Torque T _{2N}	Nm		28	60	200	360	615	1,325	-	-	-	-	
			31	60	130	250	440	990	1,510	2,550	4,810	9,565	
		2	35	70	170	310	535	1,165	1,775	3,335	-	-	
			40	40	96	220	615	1,215	-	-	-	-	
			46	24	55	160	295	660	1,005	1,700	3,400	7,125	
			50	50	120	275	535	1,170	1,775	3,340	-	-	
				61	60	130	250	440	990	1,510	2,550	4,820	9,585
			70	60	130	250	440	990	1,510	2,550	-	-	
			91	24	55	160	295	660	1,005	1,700	3,345	7,000	
			100	24	55	160	295	660	1,005	1,700	-	-	
Emergency Stop Torque T _{2NOT}	Nm	1,2	4~100										
Max. Acceleration Torque T _{2B}	Nm	1,2	4~100 I.5 times T _{2N}										
No Load Running Torque ⁽³⁾	Nm	I	4~10	0.45	0.7	1.4	3.5	7	Ш	14	-	-	
No Load Kunning Torque	INIII	2	16~100	0.2	0.3	0.6	1.3	2.2	3.5	4.5	13	21	
Backlash ⁽²⁾	anamin	I	4~10	≦ 2	≦	≦	≦	≦	≦	≦	-	-	
Backlash	arcmin	2	16~100	≦ 3	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	
Torsional Rigidity	Nm/arcmin	1,2	4~100	8	22	60	115	395	650	1,050	2,850	5,700	
Nominal Input Speed n _{IN}	rpm	I	4~10	5,000	3,600	3,600	3,000	2,700	2,400	2,100	-	-	
Trommar input speed III _N		2	16~100	5,000	4,600	4,600	4,000	3,700	3,400	3,100	2,500	2,000	
Max. Input Speed n _{IB}	rpm	I	4~10	7,000	6,000	6,000	5,000	4,500	4,000	3,500	-	-	
	·	2	16~100	7,000	7,000	7,000	6,000	5,500	5,000	4,500	4,000	3,500	
Max.Axial Load F _{2a} ⁽⁴⁾	N	1,2	4~100	1,690	2,220	4,070	8,530	17,000	26,900	39,200	101,500	143,700	
Max.Tilting Moment M _{2K} ⁽⁴⁾	Nm	1,2	4~100	120	280	480	1,310	3,530	5,920	9,230	29,100	63,300	
Operating Temp	° C	1,2	4~100				-1	0° C∼ 90°	C				
Degree of Gearbox Protection		1,2	4~100										
Lubrication		1,2	4~100				Synthetic	c lubricatio	n grease				
Mounting Position		1,2	4~100					II direction		T .			
Running Noise ⁽³⁾	dB(A)	1	4~10	≦ 58	≦ 59	≦ 64	≦ 65	≦ 66	≦ 66	≦ 66	-	_	
	\ /	2	16~100	≦ 58	≦ 59	≦ 60	≦ 63	≦ 66	≦ 66	≦ 66	≦ 68	≦ 70	
Efficiency η	%	1	4~10					≧ 97%					
/o		2	16~100					≧ 94%					

⁽I) Ratio (i = N_{in} / N_{out}) .

⁽²⁾ Backlash is measured at 2% of Nominal Output Torque T_{2N} .

⁽³⁾ The dB values are measured by gearbox with ratio 10 (1-stage) or ratio 100 (2-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

⁽⁴⁾ Applied to the output flange center at 100 rpm.

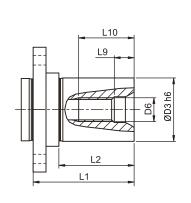
⁽⁵⁾ Continuous operation is not recommended.

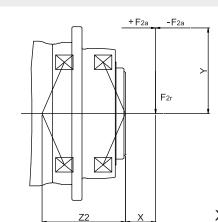
Inertia - AH Gearbox

Mode	el No.	АН	064	АН	090	АН	110	АН	140	АН	200	АН	255	АН	285	AH355	AH450
Ø ^(A)	(C3)	I-st.	2-st.	I-st.	2-st.	2-st.	2-st.										
8		-	0.1	-	-	-	-	-	-	-	-	-	-	-	-	-	-
- 11		0.17	0.16	-	0.17	-	-	-	-	-	-	-	-	-	-	-	-
14		0.21	0.2	0.53	0.21	-	0.53	-	-	-	-	-	-	-	-	-	-
19		0.63	-	0.68	0.63	1.83	0.68	-	1.83	-	-	-	-	-	-	1	-
24		-	•	4.52	•	5.04	4.52	5.63	5.04	-	5.63	-	•	-	-	ı	-
28		-	•	•	•	6.33	•	7.18	6.33	-	7.18	-	-	-	-	ı	-
32	kg.cm²	-	-	ı	-	8.73	-	10.1	8.73	12.63	10.1	-	12.63	-	-	ı	-
35		-	-	-	-	14.04	-	15.54	14.04	17.75	15.54	17.35	17.75	28.18	20.8	1	-
38		-	-	-	-	19.05	-	21.32	19.05	23.26	21.32	23.61	23.26	28.18	27.05	23.6	-
42		-	-	-	-	-	-	23.2	-	25.4	23.2	25.5	25.4	30.52	28.95	25.37	30.37
48		-	-	-	-	-	-	56.07	-	61.02	56.07	61.22	61.02	66.85	64.66	89.35	96.45
55		-	-	-	-	-	-	-	-	-	-	88.86	-	94.91	-	102	109.06
60		-	-	-	-	-	-	-	-	-	-	-	-	117.73	_	-	117.75

(A) Ø = Input shaft diameter.

Flange Shaft - AH





 $M_{2K} = \frac{F_{2a}*Y + F_{2r}*(X+Z_2)}{1000}$

 $\begin{aligned} & M_{2K}: \texttt{[Nm]} \\ & F_{2a}, F_{2r}: \texttt{[N]} \\ & X, Y, Z2: \texttt{[mm]} \end{aligned}$

Dimension	LI	L2	D3 h6	D6	L9	LI0	Order Code
811074	33	23	16	M5	4.8	12.5	FLS-AH064-S16
AH064	33	23	22	M8	7.2	19	FLS-AH064-S22
A 1 1000	41	30	22	M8	7.2	19	FLS-AH090-S22
AH090	41	30	32	MI2	10	28	FLS-AH090-S32
A11110	51	20	32	MI2	10	28	FLS-AH110-S32
AHII0	51	38	40	MI6	12	36	FLS-AH110-S40
A11140	54	38	40	MI6	12	36	FLS-AH140-S40
AH140	54	38	55	M20	15	42	FLS-AH140-S55
A11200	73	52	55	M20	15	42	FLS-AH200-S55
AH200	/3	52	75	M20	15	42	FLS-AH200-S75
AH255	150	123	90	M24	18	50	FLS-AH255-S90

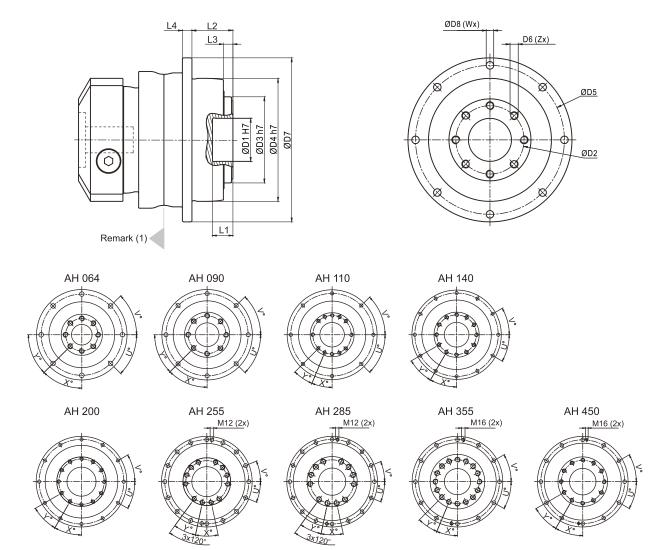
Note: Dimensions are related to gearbox flange interface.

M2K

AH / AHK	064	090	110	140	200	255	285	355	450
Z2 [mm]	63.7	84.5	106.2	90	122.8	133.2	175.5	220.6	275.3

Note: Applied to the output flange center at 100 rpm

Dimension AH Gearbox

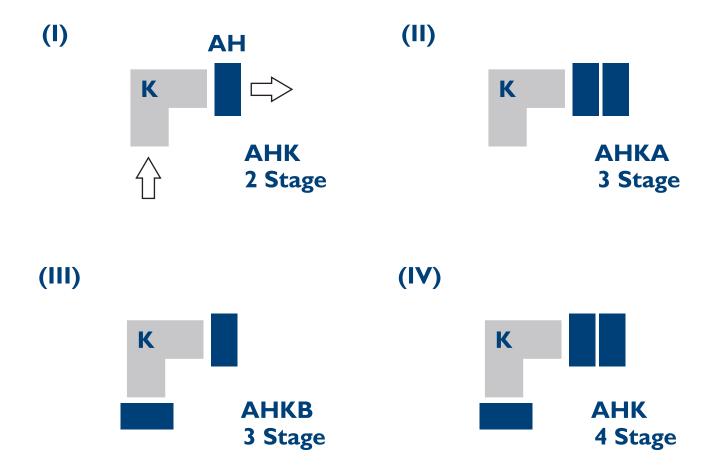


Din	nension	AH064	AH090	AHII0	AH140	AH200	AH255	AH285	AH355	AH450
DI	H7	20	31.5	40	50	80	100	100	120	155
D2		31.5	50	63	80	125	140	160	200	250
D3	h7	40	63	80	100	160	180	200	250	315
D4	h7	64	90	110	140	200	255	285	355	450
D5		79	109	135	168	233	280	310	385	490
D6 x	Pitch x Deep	M5×0.8P×8	M6x1Px10	M6x1Px11	M8x1.25Px15	M10x1.5Px20	M16x2Px25	M20x2.5Px31	M24x3Px32	M30x3.5Px40
D7		88	120	147	180	249.5	302	332	415	530
D8		4.5	5.5	5.5	6.6	9	13.5	13.5	17.5	22
LI		8	15	15	15	16	16	16	35	24
L2		19.5	30	29	38	50	66	75	80	85
L3		4	7	7	7.5	8.5	13.5	16.5	20	20
L4		5	7	8	10	12	18	20	45	60
X in [Degree	45	45	22.5	30	30	24	24	22.5	30
Y in [Degree	45	45	22.5	30	30	24	24	22.5	30
Z		8	8	12	12	12	12	12	16	12
U in [Degree	45	45	45	30	30	22.5	22.5	30	30
V in [Degree	45	45	45	30	30	22.5	22.5	30	30
W		8	8	8	12	12	16	16	12	12

Note: Dimensions are related to motor interface. Please contact APEX for details.

AHK Gearbox

AHK Structure



Performance - AHK (2 Stage) Gearbox

Model No.		Stage	Ratio	AHK064	AHK090	AHKI10	AHKI40	AHK200	AHK255	AHK285	АНК355
			12	95	195	360	615	1,315	-	-	-
			15	-	-	-	-	-	1,770	3,330	5,595
			16	95	200	360	615	1,320	-	-	-
			20	95	200	360	615	1,320	1,775	3,335	5,605
			25	80	170	310	535	1,165	1,775	3,335	5,610
Nominal Output Torque T _{2N}	Nm	2	28	92	200	360	615	1,325	-	-	-
140mmai Output forque 1 _{2N}	INM	4	35	80	170	310	535	1,170	1,775	3,340	5,615
			40	60	160	340	615	1,325	-	-	-
			49	60	130	250	440	990	1,510	2,550	4,820
			50	50	170	310	535	1,170	1,775	3,000	5,500
			70	60	130	250	440	990	1,510	2,550	4,820
			100	24	55	160	290	655	1,005	1,685	3,315
Emergency Stop Torque T _{2NOT}	Nm	2	12~100	2 times T _{2N}							
Max. Acceleration Torque T _{2B}	Nm	2	12~100				1.5 tim	es T _{2N}			
No Load Running Torque (3)	Nm	2	12~100	I	1.3	2	3.1	6	13	16	20
Backlash ⁽²⁾	arcmin	2	12~100	≦ 3	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2
Torsional Rigidity	Nm/arcmin	2	12~100	12	27	56	112	389	642	1,275	2,500
Nominal Input Speed n _{IN}	rpm	2	12~100	3,000	3,000	2,800	2,700	2,200	2,100	2,000	1,600
Max. Input Speed n _{IB}	rpm	2	12~100	6,000	6,000	6,000	4,500	4,500	4,000	3,000	2,500
Max. Axial Load F _{2a} ⁽⁴⁾	N	2	12~100	1,690	2,220	4,070	8,530	17,000	26,900	39,200	101,500
Max.Tilting Moment M _{2K} ⁽⁴⁾	Nm	2	12~100	120	280	480	1,310	3,530	5,920	9,230	29,100
Operating Temp	°C	2	12~100	00 -10° C~ 90° C							
Degree of Gearbox Protection		2	12~100								
Lubrication		2	12~100			Syı	nthetic lubri	cation greas	se		
Mounting Position		2	12~100				All dire	ctions			
Running Noise ⁽³⁾	dB(A)	2	12~100	≦ 64	≦ 66	≦ 68	≦ 68	≦ 70	≦ 70	≦ 72	≦ 74
Efficiency η	%	2	12~100	≧ 94%							

⁽I) Ratio (i = N_{in} / N_{out}) .

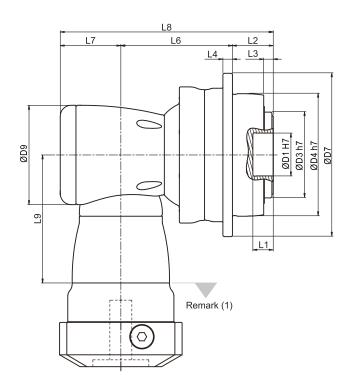
- (2) Backlash is measured at 2% of Nominal Output Torque $T_{2N}\,.$
- (3) The dB values are measured by gearbox with ratio 100 (2-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.
 - By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.
- (4) Applied to the output flange center at 100 rpm.
- (5) Continuous operation is not recommended.

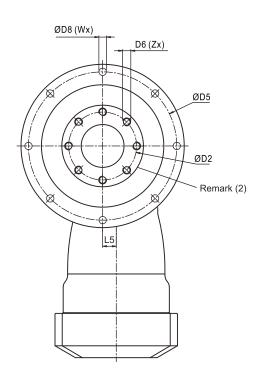
Inertia - AHK (2 Stage) Gearbox

	Model No.	AHK064	AHK090	AHKII0	AHK140	AHK200	AHK255	AHK285	AHK355
8		0.1	-	-	-		-	-	-
11		0.17	0.18	-	-	1	-	-	-
14		0.21	0.5	0.52	-		-	-	-
19		-	0.65	1.69	1.71	-	-	-	-
24		-	-	4.89	5.05	6.92	-	-	-
28		-	-	-	6.55	6.98	-	-	-
32	kg.cm²	-	-	-	9.47	10.18	10.18	-	-
35		-	-	-	14.91	15.21	15.21	15.68	-
38		-	-	-	20.69	20.7	20.7	21.69	23.46
42		-	-	-	-	22.83	22.83	23.59	25.28
48		-	-	-	-	58.45	58.45	59.3	61.61
55		-	-	-	-	-	_	-	89.67

⁽A) \emptyset = Input shaft diameter.

Dimension AHK (2 Stage) Gearbox (Ratio i = 12~100)





Dime	nsion	AHK064	AHK090	AHKI10	AHKI40	AHK200	AHK255	AHK285	AHK355
DI	H7	20	31.5	40	50	80	100	100	120
D2		31.5	50	63	80	125	140	160	200
D3	h7	40	63	80	100	160	180	200	250
D4	h7	64	90	110	140	200	255	285	355
D5		79	109	135	168	233	280	310	385
D6 x Pit	ch x Deep	M5x0.8Px8	M6xIPxI0	M6x1Px11	M8×1.25P×15	M10x1.5Px20	M16x2Px25	M20x2.5Px31	M24x3Px32
D7		88	120	147	180	249.5	302	332	415
D8		4.5	5.5	5.5	6.6	9	13.5	13.5	17.5
D9		73	94	116	163	210	210	255	300
LI		8	15	15	15	16	16	16	35
L2		19.5	30	29	38	50	66	75	80
L3		4	7	7	7.5	8.5	13.5	16.5	20
L4		5	7	8	10	12	18	20	45
L5		10	13	17	25	31	31	36	43
L6		87	90.5	114	147.5	175	191.5	249.5	290
L7		44.5	53	68.3	89	115	115	131	165
L8		151	173.5	211.3	274.5	340	372.5	455.5	535
L9		94	114.5	129	173.5	228	228	265.5	294.5
X in Deg	gree	45	45	22.5	30	30	24	24	22.5
Y in Deg	ree	45	45	22.5	30	30	24	24	22.5
Z		8	8	12	12	12	12	12	16
U in Deg	gree	45	45	45	30	30	22.5	22.5	30
V in Deg	ree	45	45	45	30	30	22.5	22.5	30
W		8	8	8	12	12	16	16	12

⁽¹⁾ Dimensions are related to motor interface. Please contact APEX for details.

⁽²⁾ Refer to the AH series (Page 05) for flange interface.

Performance - AHKA (3 Stage) Gearbox

Model No.		Stage	Ratio ⁽¹⁾	AHKA285	AHKA355	AHKA450	
			100	3,345	5,620	10,965	
			125	3,345	5,625	10,970	
			140	3,345	5,625	10,970	
			175	3,345	5,625	10,970	
Nominal Output Torque T _{2N}	NI	,	200	3,345	5,625	10,975	
Nominal Output forque 1 _{2N}	Nm	3	250	3,345	5,625	10,975	
			350	3,345	5,630	10,975	
			500	3,345	5,350	9,050	
			700	2,555	4,825	9,600	
			1,000	1,650	3,250	6,785	
Emergency Stop Torque T _{2NOT}	Nm	3	100~1,000		2 times T_{2N}		
Max. Acceleration Torque T _{2B}	Nm	3	100~1,000		1.5 times T _{2N}		
No Load Running Torque (3)	Nm	3	100~1,000	6	6	13	
Backlash ⁽²⁾	arcmin	3	100~1,000	≦ 2	≦ 2	≦ 2	
Torsional Rigidity	Nm/arcmin	3	100~1,000	1,275	2,500	5,100	
Nominal Input Speed n _{IN}	rpm	3	100~1,000	2,100	2,100	2,000	
Max. Input Speed n _{IB}	rpm	3	100~1,000	4,000	4,000	3,000	
Max.Axial Load F _{2a} ⁽⁴⁾	N	3	100~1,000	39,200	101,500	143,700	
Max.Tilting Moment M _{2K} ⁽⁴⁾	Nm	3	100~1,000	9,230	29,100	63,300	
Operating Temp	°C	3	100~1,000		-10° C~ 90° C		
Degree of Gearbox Protection		3	100~1,000	IP65			
Lubrication		3	100~1,000	Synthetic lubrication grease			
Mounting Position		3	100~1,000	All directions			
Running Noise ⁽³⁾	dB(A)	3	100~1,000	≦ 72	≦ 74	≦ 76	
Efficiency η	%	3	100~1,000	≧ 92%			

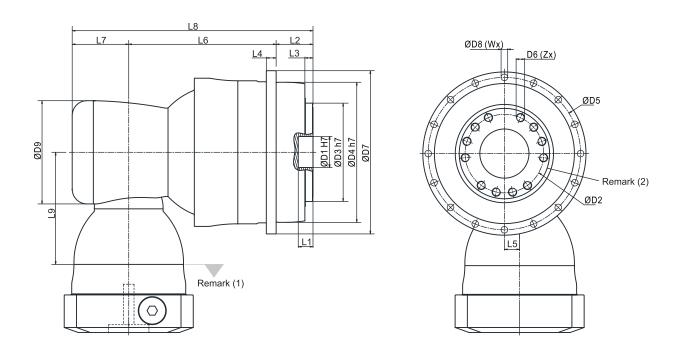
- (I) Ratio (i = N_{in} / N_{out}) .
- (2) Backlash is measured at 2% of Nominal Output Torque T_{2N} .
- (3) The dB values are measured by gearbox with ratio 1,000 (3-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.
 - By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.
- (4) Applied to the output flange center at 100 rpm.
- (5) Continuous operation is not recommended.

Inertia - AHKA (3 Stage) Gearbox

Input Shaft (C3)	Model No.	AHKA285	AHKA355	AHKA450		
32		10.18	10.18	-		
35		15.21	15.21	15.68		
38	1 2	l 2		20.7	20.7	21.69
42	kg.cm ⁻	22.83	22.83	23.59		
48		58.45	58.45	59.3		
55		-	-	86.95		

(A) \emptyset = Input shaft diameter.

Dimension AHKA (3 Stage) Gearbox (Ratio i=100~1,000)



Dimension	AHKA285	AHKA355	AHKA450
DI H7	100	120	155
D2	160	200	250
D3 h7	200	250	315
D4 h7	285	355	450
D5	310	385	490
D6 x Pitch x Deep	M20x2.5Px3 I	M24x3Px32	M30x3.5Px40
D7	332	415	530
D8	13.5	17.5	22
D9	210	210	255
LI	16	35	24
L2	75	80	85
L3	16.5	20	20
L4	20	45	60
L5	31	31	36
L6	300	332	447.5
L7	115	115	131
L8	490	527	663.5
L9	228	228	265.5
X in Degree	24	22.5	30
Y in Degree	24	22.5	30
Z	12	16	12
U in Degree	22.5	30	30
V in Degree	22.5	30	30
W	16	12	12

 $⁽I)\ Dimensions\ are\ related\ to\ motor\ interface.\ Please\ contact\ APEX\ for\ details.$

 $^{(2) \} Refer to \ the \ AH \ series (Page \ 05) \ for \ flange \ interface.$

Performance - AHKB (3 Stage) Gearbox

Model No.		Stage	Ratio ⁽¹⁾	AHKB090	AHKBI 10	AHKBI40	AHKB200	AHKB 255	AHKB285	AHKB355	
			64	200	360	615	1,325	-	-	-	
			84	200	360	620	1,325	-	-	-	
			100	200	360	620	1,330	1,780	3,345	5,620	
			125	170	310	535	1,170	1,780	3,345	5,625	
			140	200	360	620	1,330	1,780	3,345	5,625	
			175	170	310	535	1,170	1,780	3,345	5,625	
N . I O . I T	Nm		200	200	360	620	1,330	1,780	3,345	5,625	
Nominal Output Torque T _{2N}		3	250	170	310	535	1,170	1,780	3,345	5,625	
			280	200	360	620	1,330	1,510	-	-	
			350	170	310	535	1,170	1,775	3,345	5,630	
			400	160	340	620	1,330	-	-	-	
			500	170	310	535	1,170	1,780	3,000	5,500	
			700	130	250	440	990	1,510	2,555	4,825	
			1,000	55	160	290	640	980	1,655	3,250	
Emergency Stop Torque T _{2NOT}	Nm	3	64~I,000				2 times T _{2N}				
Max. Acceleration Torque T _{2B}	Nm	3	64~1,000	I.5 times T _{2N}							
No Load Running Torque (3)	Nm	3	64~1,000	0.2	0.2	0.3	0.4	I	1.2	1.5	
Backlash (2)	arcmin	3	64~I,000	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	
Torsional Rigidity	Nm/arcmin	3	64~1,000	27	56	112	389	642	1,275	2,500	
Nominal Input Speed n _{IN}	rpm	3	64~1,000	5,500	4,600	4,600	4,000	3,700	3,400	3,100	
Max. Input Speed n _{IB}	rpm	3	64~1,000	7,000	7,000	7,000	6,000	5,500	5,000	4,500	
Max. Axial Load F _{2a} ⁽⁴⁾	N	3	64~1,000	2,220	4,070	8,530	17,000	26,900	39,200	101,500	
Max.Tilting Moment M _{2K} ⁽⁴⁾	Nm	3	64~1,000	280	480	1,310	3,530	5,920	9,230	29,100	
Operating Temp	°C	3	64~1,000			-	10° C~ 90° (C			
Degree of Gearbox Protection		3	64~1,000				IP65				
Lubrication		3	64~1,000			Synthe	tic lubrication	grease			
Mounting Position		3	64~1,000				All directions				
Running Noise ⁽³⁾	dB(A)	3	64~1,000	≦ 66	≦ 68	≦ 68	≦ 70	≦ 70	≦ 72	≦ 74	
Efficiency η	%	3	64~1,000				≧ 92%			_	

⁽I) Ratio (i = N_{in} / N_{out}).

Inertia - AHKB (3 Stage) Gearbox

Innut Chaft	Model No.	AHKB 090	AHKBII0	AHKB140	AHKB 200	AHKB 255	AHKB 285	АНКВ355
8		0.17	-	-	-	-	-	-
11		0.17	0.52	ı	-	-	-	-
14		0.21	0.53	1.83	-	-	-	-
19			0.68	1.83	5.6	-	-	-
24		-	-	5.04	5.63	5.63	-	-
28		-	-	ı	7.18	7.18	-	-
32	kg.cm²		-	1	10.1	10.1	12.63	-
35			-	1	15.54	15.54	17.75	17.35
38		-	-	-	21.32	21.32	23.26	23.61
42		-	-	-	-	23.2	25.4	25.5
48		-	-	-	-	56.07	61.02	61.22

⁽A) \emptyset = Input shaft diameter.

⁽²⁾ Backlash is measured at 2% of Nominal Output Torque T_{2N} .

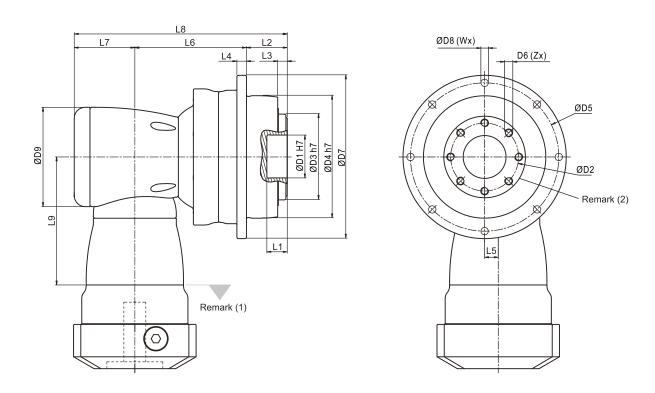
⁽³⁾ The dB values are measured by gearbox with ratio 1,000 (3-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

⁽⁴⁾ Applied to the output flange center at 100 rpm.

⁽⁵⁾ Continuous operation is not recommended.

Dimension AHKB (3 Stage) Gearbox (Ratio i=64~1,000)



Dimension	AHKB090	AHKBI10	AHKB140	AHKB200	AHKB255	AHKB285	AHKB355
DI H7	31.5	40	50	80	100	100	120
D2	50	63	80	125	140	160	200
D3 h7	63	80	100	160	180	200	250
D4 h7	90	110	140	200	255	285	355
D5	109	135	168	233	280	310	385
D6 x Pitch x Deep	M6×IP×I0	M6x1Px11	M8×1.25P×15	M10×1.5P×20	M16x2Px25	M20×2.5P×31	M24x3Px32
D7	120	147	180	249.5	302	332	415
D8	5.5	5.5	6.6	9	13.5	13.5	17.5
D9	94	116	163	210	210	255	300
LI	15	15	15	16	16	16	35
L2	30	29	38	50	66	75	80
L3	7	7	7.5	8.5	13.5	16.5	20
L4	7	8	10	12	18	20	45
L5	13	17	25	31	31	36	43
L6	90.5	114	147.5	175	191.5	249.5	290
L7	53	68.3	89	115	115	131	165
L8	173.5	211.3	274.5	340	372.5	455.5	535
L9	114.5	129	173.5	228	228	265.5	294.5
X in Degree	45	22.5	30	30	24	24	22.5
Y in Degree	45	22.5	30	30	24	24	22.5
Z	8	12	12	12	12	12	16
U in Degree	45	45	30	30	22.5	22.5	30
V in Degree	45	45	30	30	22.5	22.5	30
W	8	8	12	12	16	16	12

 $^{(1)\} Dimensions\ are\ related\ to\ motor\ interface.\ Please\ contact\ APEX\ for\ details.$

 $^{(2) \} Refer to \ the \ AH \ series (Page \ 05) \ for \ flange \ interface.$

Performance - AHK (4 Stage) Gearbox

Model No.		Stage	Ratio ⁽¹⁾	AHK285	AHK355	AHK450		
			1,225	3,350	5,630	10,980		
			1,400	3,350	5,630	10,980		
			1,750	3,350	5,630	10,980		
			2,000	3,350	5,630	10,980		
Nominal Output Torque T_{2N}	Nm	4	2,800	2,555	4,825	9,600		
			3,500	3,350	5,630	10,980		
			5,000	3,350	5,350	9,050		
			7,000	2,625	4,960	10,115		
			10,000	1,975	3,870	8,325		
Emergency Stop Torque T _{2NOT}	Nm	4	1,225~10,000	2 times T _{2N}				
$Max.Acceleration Torque T_{2B}$	Nm	4	1,225~10,000	00 I.5 times T _{2N}				
No Load Running Torque (3)	ning Torque ⁽³⁾ Nm		1,225~10,000	0.4	0.4	I		
Backlash ⁽²⁾	arcmin	4	1,225~10,000	≦ 2	≦ 2	≦ 2		
Torsional Rigidity	Nm/arcmin	4	1,225~10,000	1,275	2,500	5,100		
Nominal Input Speed n _{IN}	rpm	4	1,225~10,000	3,700	3,700	3,400		
Max. Input Speed n _{IB}	rpm	4	1,225~10,000	5,500	5,500	5,000		
Max. Axial Load F _{2a} ⁽⁴⁾	N	4	1,225~10,000	39,200	101,500	143,700		
Max.Tilting Moment M _{2K} ⁽⁴⁾	Nm	4	1,225~10,000	9,230	29,100	63,300		
Operating Temp	° C	4	1,225~10,000	-10° C~ 90° C				
Degree of Gearbox Protection		4	1,225~10,000	IP65				
Lubrication		4	1,225~10,000	Synthetic lubrication grease				
Mounting Position		4	1,225~10,000		All directions			
Running Noise ⁽³⁾	dB(A)	4	1,225~10,000	≦ 72	≦ 74	≦ 76		
Efficiency η	%	4	1,225~10,000		≧ 90%			

⁽I) Ratio (i = N_{in} / N_{out}).

By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

Inertia - AHK (4 Stage) Gearbox

Input Shaft (C3)	Model No.	AHK285	AHK355	AHK450
24		5.63	5.63	-
28		7.18	7.18	=
32	ka am²	10.1	10.1	12.63
35	kg.cm [*]	15.54	15.54	17.75
38		21.32	21.32	23.26

⁽A) \emptyset = Input shaft diameter.

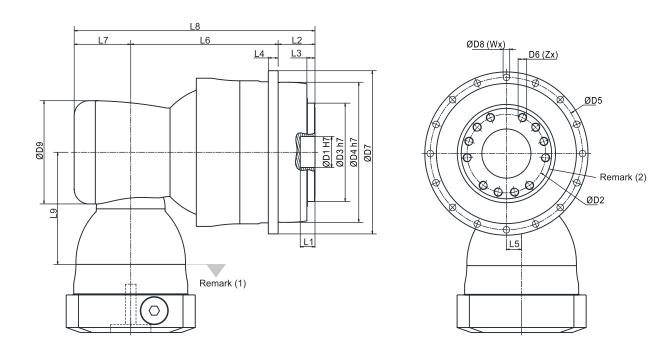
⁽²⁾ Backlash is measured at 2% of Nominal Output Torque T_{2N} .

⁽³⁾ The dB values are measured by gearbox with ratio 10,000 (4-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.

⁽⁴⁾ Applied to the output flange center at 100 rpm.

⁽⁵⁾ Continuous operation is not recommended.

Dimension AHK (4 Stage) Gearbox(Ratio i = 1,225~10,000)



Dimension	AHK285	AHK355	AHK450
DI H7	100	120	155
D2	160	200	250
D3 h7	200	250	315
D4 h7	285	355	450
D5	310	385	490
D6 x Pitch x Deep	M20x2.5Px3 I	M24x3Px32	M30x3.5Px40
D7	332	415	530
D8	13.5	17.5	22
D9	210	210	255
LI	16	35	24
L2	75	80	85
L3	16.5	20	20
L4	20	45	60
L5	31	31	36
L6	300	332	447.5
L7	115	115	131
L8	490	527	663.5
L9	228	228	265.5
X in Degree	24	22.5	30
Y in Degree	24	22.5	30
Z	12	16	12
U in Degree	22.5	30	30
V in Degree	22.5	30	30
W	16	12	12

 $^{(1)\} Dimensions\ are\ related\ to\ motor\ interface.\ Please\ contact\ APEX\ for\ details.$

 $^{(2) \} Refer to \ the \ AH \ series (Page \ 05) \ for \ flange \ interface.$

Performance AHKC Gearbox

Model No.		Stage	Ratio ⁽¹⁾	AHKC064	AHKC090	AHKCI10	AHKC140	AHKC200	AHKC255	AHKC285	AHKC355	AHKC450		
			4	95	195	355	605	1,300	-	-	-	-		
			5	80	165	305	525	1,150	1,755	3,305	-	-		
		2	7	60	130	250	440	985	1,500	2,535	-	-		
	Nm -		8	95	195	360	610	1,315	-	-	-	-		
Nominal Output Torque T _{2N}			10	80	165	310	530	1,160	1,765	3,325	-	-		
Trommar Suspas for que 1 2N			21	-	165	310	535	1,165	1,510	3,335	5,600	10,930		
			31	-	130	250	440	990	1,775	2,550	4,815	9,580		
		3	46	-	55	160	295	665	1,015	1,715	3,380	7,055		
			61	-	130	250	440	990	1,775	2,550	4,820	9,590		
			91	-	55	160	295	660	1,000	1,690	3,330	6,950		
Emergency Stop Torque T _{2NOT}	Nm	2,3	4~91		2 times T_{2N}									
Max. Acceleration Torque T _{2B}	Nm	2,3	4~91				I	.5 times T ₂	2N					
(3)		2	4~10	2	2.5	5.8	12	25	48	95	-	-		
No Load Running Torque ⁽³⁾	Nm	3	21~91	ı	1.5	2.5	4	9	18.5	35	75	148		
(2)		2	4~10	≦ 3	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	-	-		
Backlash ⁽²⁾	arcmin	3	21~91	-	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2	≦ 2		
Torsional Rigidity	Nm/arcmin	2,3	4~91	12	27	56	112	389	642	1,275	2,500	5,100		
Nominal Input Speed n _{IN}	rpm	2	4~10	5,000	3,600	3,000	2,300	1,800	1,500	1,100	-	-		
Nominal Input Speed II _{IN}	1 Pill	3	21~91	-	4,600	4,000	3,000	2,300	1,800	1,500	1,500	1,100		
Max. Input Speed n _{IB}	rpm		4~10	7,000	6,000	5,500	4,500	3,500	3,000	2,200	-	-		
Tiax. Input Speed IIIB	1 7	3	21~91	-	7,000	6,500	5,500	4,500	3,500	3,000	3,000	2,200		
Max. Axial Load F _{2a} ⁽⁴⁾	N	2,3	4~91	1,690	2,220	4,070	8,530	17,000	26,900	39,200	101,500	143,700		
Max. Tilting Moment M _{2K} ⁽⁴⁾	Nm	2,3	4~91	120	280	480	1,310	3,530	5,920	9,230	29,100	63,300		
Operating Temp	°C	2,3	4~91				-1	0° C∼ 90°	, C					
Degree of Gearbox Protection		2,3	4~91					IP65						
Lubrication		2,3	4~91				Synthetic	c lubricatio	n grease					
Mounting Position		2,3	4~91				All	directions						
Running Noise ⁽³⁾			4~10	≦68	≦ 68	≦ 68	≦ 70	≦ 70	≦ 72	≦ 74	-	-		
Truming House	(A)	3	21~91	-	≦ 68	≦ 68	≦ 70	≦ 70	≦ 72	≦ 74	≦ 74	≦ 76		
Efficiency η	%	2	4~10					≧ 95%						
(I) Paris (:= NL (NL)	/0	3	21~91					≧ 93%						

 $[\]overline{(I) \text{ Ratio } (i = N_{in} / N_{out})}$.

Inertia AHKC Gearbox (Ratio i=4~10/21~91)

Mode	el No.	AHKC064	АНК	C090	АНК	CII0	АНК	C140	АНК	C200	АНК	C255	АНК	C285	AHKC355	AHKC450
Ø ^(A)	(C3)	2-st.	2-st.	3-st.	2-st.	3-st.	3-st.	3-st.								
8		0.1	-	0.1	-	-	-	-	-	-	-	-	-	-	-	-
П		0.17	0.52	0.17	-	-	-	-	-	-	-	-	-	-	-	-
14		0.21	0.52	0.21	-	0.52	-	-	-	-	-	-	-	-	-	-
19		0.62	1.69	0.62	1.71	1.69	-	1.71	-	-	-	-	•	•	-	ı
24	kg.cm²	-	4.89	-	5.05	4.89	6.92	5.05	-	6.92	-	-	•	ı	-	ı
28	ky.ciii	-	-	-	6.55	-	6.98	6.55	-	6.98	-	-	-	•	-	ı
32		-	-	-	9.47	-	10.18	9.47	10.18	10.18	-	10.18	-	-	-	-
35		-	-	-	14.91	-	15.21	14.91	15.21	15.21	15.68	15.21	23.46	15.68	-	ı
38		-	-	-	20.69	-	20.7	20.69	20.7	20.7	21.69	20.7	23.46	21.69	21.69	ı
42		-	-	-	-	-	22.83	-	22.83	22.83	23.59	22.83	25.28	23.59	23.59	25.28
48		-	-	-	-	-	58.45	-	58.45	58.45	59.3	58.45	61.61	59.3	59.3	61.61
55		-	-	-	-	-	-	-	-	-	86.95	-	89.67	•	86.95	89.67
60		-	-	-	-	-	-	-	-	-	-	-	112.49	-	-	112.49

⁽A) Ø = Input shaft diameter.

⁽²⁾ Backlash is measured at 2% of Nominal Output Torque $T_{\scriptscriptstyle 2N}$.

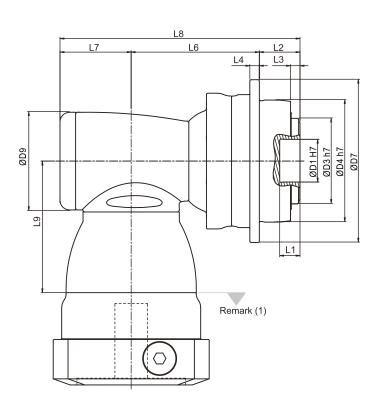
⁽³⁾ The dB values are measured by gearbox with ratio 10 (2-stage) or ratio 91 (3-stage), no loading at 3,000 RPM or at the respective Nominal Input Speed by bigger model size.

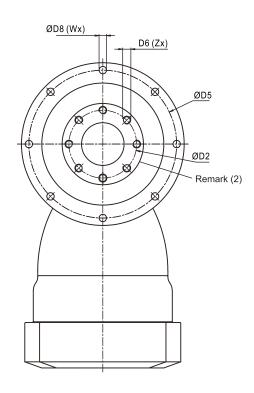
By lower ratio and/or higher RPM, the noise level could be 3 to 5 dB higher.

⁽⁴⁾ Applied to the output flange center at 100 rpm.

⁽⁵⁾ Continuous operation is not recommended.

Dimension AHKC Gearbox (Ratio i=4~10/21~91)



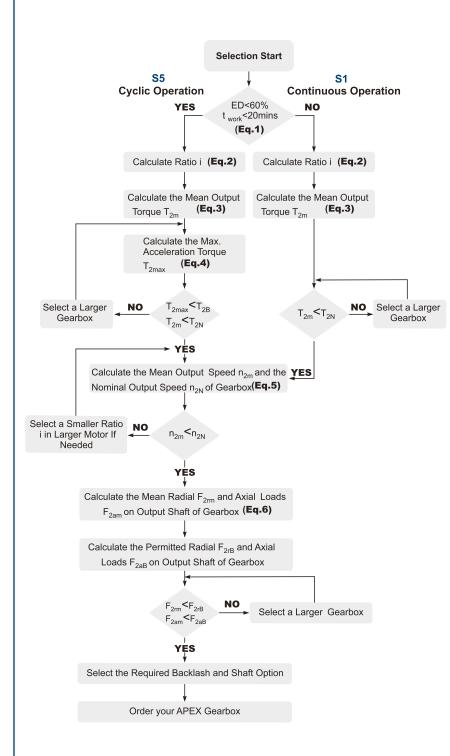


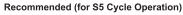
Dimension AHKC064 AHKC090 AHKC110 AHKC1		C140	АНК	C200	АНК	C255	АНК	C285	AHKC355	AHKC450						
Dimens	sion	2-st.	2-st.	3-st.	2-st.	-st. 3-st. 2		3-st.	2-st.	3-st.	2-st.	3-st.	2-st.	3-st.	3-st.	3-st.
DI	H7	20	31	.5	4	0	50		80		100		100		120	155
D2		31.5	5	0	6	63		80		125		40	10	60	200	250
D3	h7	40	6	3	8	80		00	10	60	18	30	20	00	250	315
D4	h7	64	9	0	I	110		40	20	00	2.	55	2	85	355	450
D5		79	10)9	13	135		68	2:	33	28	30	3	10	385	490
D6 x Pitch	х Деер	M5x0.8Px8	M6x1	P×10	M6x1	M6xIPxII M		25P×15	MI0xI	.5Px20	MI6x	2Px25	M20×2	2.5Px31	M24x3Px32	M30x3.5Px40
D7		88	13	20	14	147		80	24	9.5	3(02	3:	32	415	530
D8		4.5	5	.5	5	5.5		.6	•	9	13	3.5	13	3.5	17.5	22
D9		64	92	64	116	116 92		116	156	156	195	156	240	195	195	240
LI		8	ı	5	ı	15		15		16		6	16		35	24
L2		19.5	3	0	2	29		38		0	6	6	75		80	85
L3		4		7		7		7.5		.5	13	3.5	16	6.5	20	20
L4		5		7	8	3	10		ı	2	1	8	2	20	45	60
L6		92	100.5	121.5	124.5	142	175.5	174.5	185	244.5	199	264.5	265.5	307.5	339.5	463.5
L7		46.5	61.5	46.5	76	61.5	97.5	76	97.5	97.5	105.5	97.5	141	105.5	105.5	141
L8		158	192	198	229.5	232.5	311	288.5	332.5	392	370.5	428	481.5	488	525	689.5
L9		81.5	113.5	81.5	147.5	113.5	196.5	147.5	196.5	196.5	229	196.5	260	229	229	260
X in Degre	ee	45	4	5	22	22.5		0	3	0	2	.4	2	24	22.5	30
Y in Degre	ee	45	4	5	22	22.5		0	3	0	2	4	2	24	22.5	30
Z		8	1	3	I	12		2	I	2		2	12		16	12
U in Degre	ee	45	4	5	4	45		30		30		22.5		2.5	30	30
V in Degre	ee	45	4	5	4	·5	3	0	3	0	22.5		22.5		30	30
W		8		3		3	I	2	I	2		6	I	6	12	12

⁽¹⁾ Dimensions are related to motor interface. Please contact APEX for details.

 $^{(2) \} Refer to the AH \ series (Page \ 05) \ for \ flange \ interface.$

Selection of the optimum gearbox





The general design is given for

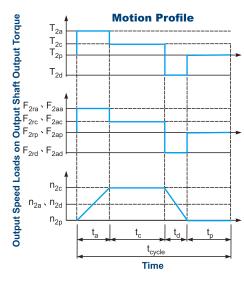
$$\frac{J_L}{J_{i2}} \le 4 \times J_m$$

The optimal design is given for

$$\frac{J_L}{I_2} \cong J_m$$

J_L Load Inertia

J_m Motor Inertia



1. ED =
$$\frac{t_a + t_c + t_d}{t_{cycle}}$$
 x 100%, $t_{work} = t_a + t_c + t_d$

Index : a. Acceleration, c. Constant,
d. Deceleration, p. Pause (Eq.1)

$$\textbf{2.} \ \textbf{i} \cong \frac{\textbf{n}_{m}}{\textbf{n}_{work}}$$

n_m Output Speed of the Motor

$$n_{work}$$
 Working Speed (Eq.2)

3.
$$T_{2m} = 3\sqrt{\frac{n_{2a} \times t_a \times T_{2a}^3 + n_{2c} \times t_c \times T_{2c}^3 + n_{2d} \times t_d \times T_{2d}^3}{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}}$$
(Eq.3)

$$\mathbf{4.} \, \mathsf{T}_{\mathsf{2max}} = \mathsf{T}_{\mathsf{mB}} \, \mathsf{x} \, \mathsf{i} \, \mathsf{x} \, \mathsf{K}_{\mathsf{s}} \, \mathsf{x} \mathsf{\eta}$$

where K_s is

K _s	No. of Cycles / hr
1.0	0 ~ 1,000
1.1	1,000 ~ 1,500
1.3	1,500 ~ 2,000
1.6	2.000 ~ 3,000
1.8	3.000 ~ 5,000

T_{mB} Max. Output Torque of the Motor

 η Efficency of the Gearbox (Eq.4)

5.
$$n_{2a} = n_{2d} = \frac{1}{2} \times n_{2c}$$

$$n_{2m} = \frac{n_{2a} \times t_a + n_{2c} \times t_c + n_{2d} \times t_d}{t_a + t_c + t_d}$$

$$n_{2N} = \frac{n_{1N}}{i}$$
(Eq.5)

$$\mathbf{6.} \, \mathsf{F}_{2\mathsf{rm}} = \, 3 \sqrt{\frac{\mathsf{n}_{2\mathsf{a}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{a}} \, \mathsf{x} \, \mathsf{F}_{2\mathsf{ra}}^{ + \mathsf{n}_{2\mathsf{c}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{c}} \, \mathsf{x} \, \mathsf{F}_{2\mathsf{rc}}^{ + \mathsf{n}_{2\mathsf{d}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{d}} \, \mathsf{x} \, \mathsf{F}_{2\mathsf{rd}}^{ }}{\mathsf{n}_{2\mathsf{a}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{d}} \, \mathsf{n}_{2\mathsf{c}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{c}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{c}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{d}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{d}} \, \mathsf{x} \, \mathsf{f}_{\mathsf{d}} \, \mathsf{x} \, \mathsf{f}_{\mathsf{d}} \, \mathsf{x} \, \mathsf{f}_{\mathsf{d}} \, \mathsf{x} \, \mathsf{f}_{\mathsf{d}} \, \mathsf{x}}}} \\ \mathsf{F}_{\mathsf{2\mathsf{a\mathsf{m}}}} = \, 3 \sqrt{\frac{\mathsf{n}_{\mathsf{2\mathsf{a}}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{a}} \, \mathsf{x} \, \mathsf{F}_{\mathsf{2\mathsf{a\mathsf{a}}}^{ } + \mathsf{n}_{\mathsf{2\mathsf{c}}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{c}} \, \mathsf{x} \, \mathsf{F}_{\mathsf{2\mathsf{a\mathsf{d}}}^{ } + \mathsf{n}_{\mathsf{2\mathsf{d}}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{d}} \, \mathsf{x}}}}{\mathsf{n}_{\mathsf{2\mathsf{a}}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{a}} \, \mathsf{x} \, \mathsf{F}_{\mathsf{2\mathsf{a\mathsf{a}}}^{ } + \mathsf{n}_{\mathsf{2\mathsf{c}}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{c}} \, \mathsf{x} \, \mathsf{F}_{\mathsf{2\mathsf{d}}} \, \mathsf{x} \, \mathsf{t}_{\mathsf{d}} \, \mathsf{x} \, \mathsf{F}_{\mathsf{2\mathsf{d}}} \, \mathsf{d}}}}$$

Glossary

Emergency Stop Torque T _{2NOT}	Nm	The Emergency Stop Torque is the maximum permitted torque at the output of gearbox. This may happen only occasionally and may not exceed 1,000 times during the whole service life.
Max. Acceleration Torque T _{2B}	Nm	Under the Cyclic Operation (S5), the Max. Acceleration Torque is the maximum torque which can be transmitted only briefly to the output of gearbox up to 1,000 cycles/hr.
No Load Running Torque	Nm	The No Load Running Torque is the min. torque to overcome the internal friction of a gearbox without loading*.
Nominal Input Speed n _{1N}	rpm	The Nominal Input Speed is the permitted input speed of gearbox by the Continuous Operation (S1) while the housing temperature does not exceed 90°C. This value is measured at environment temperature 25°C.
Max. Input Speed n _{1B}	rpm	The Max. Input Speed is the max. permitted input speed of gearbox by the Cyclic operation (S5). This value is measured at environment temperature 25°C and serves as the absolute limit of the gearbox.
Backlash	arcmin	The Backlash is the maximum angular measurement between two teeth of gears when the transverse operation occurs (refer to Diagram 1). The arcmin is the measurement unit for the backlash. One arcmin equals 1/ 60 degree, symbolized as 1'. Operating pitch circles Diagram 1 Diagram 1
Torsional Rigidity	Nm/arcmin	Torsional Rigidity is the quotient $(\triangle T / \triangle \emptyset)$ between the applied torque and resulting torsion angle. This value indicates how much torque is needed on the gearbox by to rotate the output shaft for 1 arcmin. The Torsional Rigidity can be determined by Hysteresis Curve. Hysteresis Curve When the input shaft is locked, increase torque at the output slowly up to T_{2B} in both directions and then release the torque gradually. According to the measured torque and torsion angle, a closed curve will be acquired as in the Diagram 2.
Radial Load And Axial Load	N	The permitted radial and axial loads on output shaft of the gearbox depend on the design of the gearbox supporting bearings. For more information, please refer to APEX website. F2r Radial Load F2a Axial Load
Efficiency η	%	The transmission efficiency of the gears inside a gearbox (without friction).
Operating Temperature	° C	The Operating Temperature indicates the temperature of gearbox housing.
Degree of Protection		IP code stands for International Protection standard. The IP65 as example: the first IP number stands for protection degree against dust; the second IP number stands for protection against liquid.
Lubrication		APEX uses synthetic lubrication grease. Alternate greases are available, please contact APEX.
Running Noise	dB(A)	The Running Noise is measured depends on gearbox size, the ratio and the speed*. Higher speed usually induces higher noise level, while higher ratio induces lower noise level.
Moment of Inertia J₁	kg.cm²	The Moment of Inertia J1 is a measurement of the effort applied to an object to maintain its momentary condition at rest or rotating.
Dragkova Torrus		The Breakaway Torque is the minimum torque to start the rotation from the input side of gearbox.
Breakaway Torque	Nm	A smaller size or a higher ratio gearbox requests less Breakaway Torque.

 $^{^*}$ This value is measured at environment temperature 25°C and the input speed 3,000 rpm. If the Nominal Input Speed n_{1N} of gearbox is lower than 3,000 rpm, this value is measured by that specific Nominal Input Speed.